

THE FLOW OF TWO IMMISCIBLE FLUIDS  
IN A ONE-DIMENSIONAL POROUS MEDIUM AND FINITE ELEMENTS

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1. Introduction

The mathematical formulation of the physical phenomenon is

Problem P<sub>y</sub>: Find a pair  $U, s$  defined in  $I \times \tau$ ,  $\tau$  with

$$(1.1) \quad I = (-1, 1), \quad \tau = (0, T)$$

according to

$$(1.2) \quad U_t = \begin{cases} U_{yy} & \text{in } (-1, s) \times \tau, \\ \alpha U_{yy} & \text{in } (s, 1) \times \tau, \end{cases}$$

$$(1.3) \quad U(\pm 1, \cdot) = f_{\pm} \quad \text{in } \tau,$$

$$(1.4) \quad U(\cdot, 0) = g \quad \text{in } I$$

together with

$$(1.5) \quad U(s(t)^-, t) = U(s(t)^+, t) \quad \text{in } \tau,$$

$$(1.6) \quad -\dot{s}(t) = U_y(s(t)^-, t) = U_y(s(t)^+, t) \quad \text{in } \tau,$$

$$(1.7) \quad s(0) = 0.$$

With respect to the physical interpretation as well as the question of existence and unicity we refer to [1] - [4]. The moving of the interface  $s(t)$  together with the transient conditions cause special difficulties.

In [8] - [11] we analyzed a finite element method for another class of free boundary problems which covers the three problems discussed in [5]. On the one hand this

approach gives a tool for the numerical solution. On the other hand it can be used in order to derive existence and regularity results in an elementary way.

The main features of the method are: (1) The free boundary problem is transformed to a (nonlinear) boundary problem with fixed boundary. (11) The solution  $u$  is characterized by a variational equation of the type ( $H$  being an appropriate Hilbert-space)

Problem P: Find  $u = u(.,t) \in H$  according to

$$(1.8) \quad a(u, v) + b(u, v) = N(u, v) + L(v)$$

for all  $v \in H$  and  $t \in \tau$  with  $u(.,0)$  given.

Here  $a$  respective  $b$  denote positive definite respective semi-definite bilinear forms and the bounded, Frechet differentiable nonlinearity  $N$  admits an estimate

$$(1.9) \quad N(v, v) \leq \delta b(v, v) + c a(v, v)^Y$$

with  $\delta < 1$  and some  $\gamma > 0$ . The finite element method  $P_h$  defines for a given approximation space  $S_h$  an approximation  $u_h \in S_h$  via (1.8) with  $v$  restricted to  $S_h$ . By more or less standard arguments the existence of a time interval  $\tau$  can be proved such that problems  $P$  and  $P_h$  admit unique solutions in  $\tau$ .

The difference  $e$  between the solutions  $u$  and  $u_h$ , i.e. the error of the method, solves an equation of the form

(1.10)  $a(e, X) + b(e, X) = N'_u(e, X) + Q(e, X)$  for  $X \in S_h$  with  $Q$  being at least quadratic in  $e$ . The error analysis is obvious provided a Garding type inequality

$$(1.11) \quad |N'_u(v, v)| \leq b(v, v) + \lambda a(v, v)$$

for some  $\lambda \in \mathbb{R}$  holds.

In this paper we develop such a method for problem  $P_U$ . The error analysis and the application to an existence proof etc. will be given elsewhere.

## 2. A Weak Formulation

The linear transformations

$$(2.1) \quad \begin{aligned} y &= -1 + (1+s)(1+x) \\ y &= 1 - (1-s)(1-x) \end{aligned} ,$$

map the intervals  $I_- = (-1, 0)$  resp.  $I_+ = (0, 1)$  onto  $(-1, s)$  resp.  $(s, 1)$ . We introduce the new unknown  $u$  by

$$(2.2) \quad u(x, t) = U(y, t) .$$

Then  $P_U$  leads to

Problem  $P_U$ : Find a pair  $u, s$  defined in  $I \times \tau$ ,  $\tau$  according to

$$(2.3) \quad u_t = \begin{cases} (1+s)^{-2} u_{xx} + (1+s)^{-1}(1+x) \dot{s} u_x & \text{in } I_- \times \tau \\ \alpha(1-s)^{-2} u_{xx} + (1-s)^{-1}(1-x) \dot{s} u_x & \text{in } I_+ \times \tau \end{cases} ,$$

$$(2.4) \quad u(\pm 1, t) = f_{\pm}(t) \quad \text{in } \tau ,$$

$$(2.5) \quad u(x, 0) = g(x) \quad \text{in } I ,$$

together with

$$(2.6) \quad u_- = u_+ \quad \text{in } \tau ,$$

$$(2.7) \quad -\dot{s} = (1+s)^{-1} u_+^1 = \alpha(1-s)^{-1} u_+^1 \quad \text{in } \tau ,$$

$$(2.8) \quad s(0) = 0 .$$

Here and in the following  $u_+$  etc. means

$$(2.9) \quad u_+ = u_+(t) = \lim_{x \rightarrow 0^+} u(x, t)$$

and  $\dot{u}, u'$  will denote the derivatives with respect to time and space.

In the case of a 'classical solution' all the functions entering  $P_U$  are continuous. Obviously  $P_U$  remains meaningful if  $u$  and  $s$  have the reduced regularity

$$(2.10) \quad \begin{aligned} &I_1) \quad u \in L_{\infty}(\tau, \dot{H}_2) \quad \text{with} \\ &I_2) \quad \dot{u} \in L_{\infty}(\tau, H_1(I)) , \\ &II) \quad s \in W_{\infty}^1(\tau) . \end{aligned}$$

Remark: Condition  $I_2$  could be lowered but this is the adequate one for our purposes.

We will reformulate condition (2.7). Let us introduce the functionals

$$(2.11) \quad \begin{aligned} \lambda(u) &= \lambda(s; u) := \frac{1}{2} \{ \alpha(1-s)^{-1} u_+^1 - (1+s)^{-1} u_-^1 \} \\ \mu(u) &= \mu(s; u) := \frac{1}{2} \{ \alpha(1-s)^{-1} u_+^1 + (1+s)^{-1} u_-^1 \} . \end{aligned}$$

Then (2.7) can be splitted into

$$(2.12) \quad \begin{aligned} \lambda(s;u) &= 0 \\ \dot{s} &= -u(s;u) \end{aligned} \quad ,$$

Multiplication of (2.3) by  $w''$  with  $w \in \dot{H}_2$  and integration over  $I_+$  lead to

$$(2.13) \quad \begin{aligned} (\dot{u}, w'')_- &= (1+s)^{-2} (u'', w'')_- + \dot{s} (1+s)^{-1} ((1+x)u', w'')_- \\ &= \dot{u}w' \Big|_{-1}^0 - (\dot{u}', w')_- \quad , \end{aligned}$$

$$(2.14) \quad \begin{aligned} (\dot{u}, w'')_+ &= \alpha(1-s)^{-2} (u'', w'')_+ + \dot{s} (1-s)^{-1} ((1-x)u', w'')_+ \\ &= \dot{u}w' \Big|_0^1 - (\dot{u}', w')_+ \quad . \end{aligned}$$

Here  $(\cdot, \cdot)_\pm$  are the  $L_2$ -inner products with respect to  $I_\pm$ . The contribution of  $u$  in the terms  $\dot{u}w'$  at the points  $x = \pm 1$  is given by the data (2.4). The continuity condition (2.6) implies

$$(2.15) \quad \dot{u}_+ = \dot{u}_- =: \dot{u}_0 \quad .$$

Therefore in (2.13) resp. (2.14) the terms  $\dot{u}_0 w'_\pm$  resp.  $-\dot{u}_0 w'_\pm$  enter. The variational formulation will be won by a linear combination of (2.13) and (2.14). For reasons which will

become evident below we want to have a contribution  $\dot{u}_0 \lambda(s;w)$ .

Thus we have to multiply (2.13) by  $(1+s)^{-1}$  and (2.14) by  $\alpha(1-s)^{-1}$  and to add both equations. Then we get the relations taking into account (2.12)

$$(2.16) \quad a(\dot{u}, w) + b(u, w) = \mu(u) q(u, w) - 2\dot{u}_0 \lambda(w) + L(w)$$

with

$$(2.17) \quad a(v, z) = a(s;v, z) := (1+s)^{-1} (v', z')_- + \alpha(1-s)^{-1} (v', z')_+ ,$$

$$(2.18) \quad b(v, z) = b(s;v, z) := (1+s)^{-2} (v'', z'')_- + \alpha^2(1-s)^{-2} (v'', z'')_+ ,$$

$$(2.19) \quad \begin{aligned} q(v, z) &= q(s;v, z) := (1+s)^{-2} ((1+x)v', z'')_- + \\ &\quad + \alpha(1-s)^{-2} ((1+x)v', z'')_+ \quad , \end{aligned}$$

$$(2.20) \quad L(z) = L(s; z) := \alpha(1-s)^{-1} \dot{f}_+ w'_{+1} - (1+s)^{-1} \dot{f}_- w'_{-1} .$$

In order to get the needed coerciveness properties we have to replace  $\dot{u}_0$ . For the sake of symmetry we take the arithmetic mean of the right hand sides of (2.3). Using the fact  $\lambda = 0$  and  $\dot{s} = -u$  we come to

$$(2.21) \quad \begin{aligned} 2\dot{u}_0 &= M(u) = M(s;u) := (1+s)^{-2} u''_- + \alpha(1-s)^{-2} u''_+ - \\ &\quad - \alpha^{-1}(1+\alpha) \mu^2(u) \quad . \end{aligned}$$

Finally we may add a term

$$(2.22) \quad v \lambda(u) \lambda(w)$$

since this vanishes anyway. Now we are ready to define

A pair  $u, s$  having the reduced regularity  $\underline{RR}$

is a weak solution if for all  $w \in \dot{H}_2$  and almost all

$$t \in \tau$$

$$(2.23) \quad a(u, w) + b(u, w) + \gamma \lambda(u) \lambda(w) = u(u) q(u, w) - M(u) \lambda(w) + L(w)$$

and in addition for almost all  $t \in \tau$

$$(2.24) \quad \dot{s} = -u(u)$$

together with the initial conditions

$$(2.25) \quad u(\cdot, 0) = g \quad \text{in } I,$$

$$(2.26) \quad s(0) = 0.$$

A straight forward analysis shows for  $\gamma \neq 0$ :

Lemma 1: Let  $u, s$  be a weak solution and both functions sufficiently smooth then they solve  $P_u$ .

### 3. The Finite Element Method

Let for  $h < 1$

$$(3.1) \quad T_h := \{x_1 | -1 = x_0 < x_1 < \dots < x_n = 1\}$$

be a subdivision of  $I$  such that  $x = 0$  is one of the knots and with some  $n > 0$  fixed

$$(3.2) \quad n h \leq \inf (x_{i+1} - x_i) \leq \sup (x_{i+1} - x_i) \leq h.$$

The approximation spaces we will work with consist of all splines of a fixed degree  $r$  continuous in  $I$ , continuously differentiable in  $I_+$  and  $I_-$  and with a possible jump of the first derivative at  $x = 0$ . The finite element approximation is defined by

Problem  $P_u$ : Find a pair  $u_h, s_h$  with  $u_h(\cdot, t) \in S_h$  according to

$$a(s_h; u_h, x) + b(s_h; u_h, x) + \gamma_h \lambda(s_h; u_h) \lambda(s_h; x) =$$

$$(3.3) \quad = u(s_h; u_h) q(s_h; u_h, x) - M(s_h; u_h) \lambda(s_h; x) + L(s_h; x)$$

for  $x \in S_h$  and  $t \in \tau$ ,

$$(3.4) \quad \dot{s}_h = -u(s_h; u_h) \quad \text{for } t \in \tau,$$

$$(3.5) \quad u_h(\cdot, 0) = P_h g,$$

$$(3.6) \quad s_h(0) = 0$$

with  $P_h$  being the  $L_2$ -projection onto  $S_h$ .



Remark: The formulae are somewhat lengthy. But besides the point evaluations  $\lambda, u$  and  $M$  only  $L_2$ -scalar-products are to be computed. Also a time stepping procedure does not cause difficulties.

In general, i.e. in the space  $\dot{H}_2$ , no coerciveness relation of the type (1.9) will hold. This is due to the fact that  $M(u)$  depends on  $u_t''$  whereas in  $b(\cdot, \cdot)$  only the  $L_2$ -norm of  $u''$  is covered. But still we can show

Lemma 2: Assume  $s_h$  is bounded away from  $\pm 1$ . There exists a constant  $\gamma_0$  such that for any choice

$$(3.7) \quad \gamma_h \geq \gamma_0 h^{-1}$$

the term

$$(3.8) \quad u(s_h; \omega) q(s_h; \omega, \dot{\omega}) - M(s_h; \omega) \lambda(s_h; \omega)$$

appearing on the right hand side of (3.3) is bounded by

$$(3.9) \quad \delta \{ b(s_h; \omega, \dot{\omega}) + \gamma_h \lambda^2(s_h; \omega) \} + c \{ a(s_h; \omega, \dot{\omega})^2 + a(s_h; \omega, \omega)^2 \}.$$

Proof: In the following  $c_1, c_2, \dots$  denote numerical constants. If they are strictly positive we write  $\underline{c}_\nu$ . We will need the two a priori estimates:

Proposition 1: Let  $J$  be a bounded interval. For  $v \in H_1(J)$  the  $L_\infty$ -norm may be bounded by

$$(3.10) \quad \|v\|_{L_\infty(J)} \leq c_1 \{ \|v\|_{L_2(J)}^{1/2} + \|v\|_{L_2(J)} \|v'\|_{L_2(J)}^{1/2} \}.$$

Proposition 2: Let  $J$  be  $I_-$  resp.  $I_+$ . Under the above assumptions on  $s_h$  inverse relations of the type

$$(3.11) \quad \begin{aligned} \|\varphi''\|_{L_\infty(J)} &\leq c_2 h^{-1/2} \|\varphi''\|_{L_2(J)}, \\ \|\varphi''\|_{L_2(J)} &\leq c_2 h^{-1} \|\varphi'\|_{L_2(J)} \end{aligned}$$

hold for  $\varphi \in S_h$ .

Remark: (3.11) is proved in [6].

Because of the assumption there is a  $c_3 < 1$  with

$$(3.12) \quad |s_h| \leq c_3.$$

This gives at once

$$(3.13) \quad \begin{aligned} a(z, z) &\geq \underline{c}_4 \|z'\|^2, \\ b(z, z) &\geq \underline{c}_5 \|z''\|^2. \end{aligned}$$

$\|\cdot\|$  denotes the  $L_2(I)$ -norm. For functions in the space  $\dot{H}_2$  the second derivatives are defined in  $I_+$  and are in  $L_2(I_+)$ . In this way  $\|z''\|$  has to be understood.

Further we find the bounds

$$(3.14) \quad |u(z)| \leq c_6 \{ \|z'\| + \|z'\|^{1/2} \|z''\|^{1/2} \},$$

$$(3.15) \quad |q(z, z)| \leq c_7 \|z'\| \|z''\|.$$

For functions  $\varphi \in S_h$  we get because of Proposition 2

$$(3.16) \quad |M(\varphi)| \leq c_8 h^{-1/2} \|\varphi''\| + c_9 \{ \|\varphi'\|^2 + \|\varphi'\| \|\varphi''\| \}.$$

In this way we come to the estimate of the first term in

(3.8):

$$(3.17) \quad |\mu(\varphi) q(\varphi, \varphi)| \leq c_{10} \{ \|\varphi'\|^2 \|\varphi''\| + \|\varphi'\|^{3/2} \|\varphi''\|^{3/2} \}$$

which by means of Young's inequality may be estimated by

$$(3.18) \quad |\mu(\varphi) q(\varphi, \varphi)| \leq \delta \|\varphi''\|^2 + c_{11}(\delta) \{ \|\varphi'\|^4 + \|\varphi'\|^6 \}$$

with  $\delta \in (0, 1)$  arbitrary and  $c_{11}(\delta)$  depending on the constants  $c_1, \dots, c_{10}$  and on  $1 + \delta^{-1}$ .

The second term in (3.8) may be estimated by

$$(3.19) \quad |M(\varphi) \lambda(\varphi)| \leq c_{12} |\lambda(\varphi)| \{ h^{-1/2} \|\varphi''\| + \|\varphi'\|^2 + \|\varphi'\| \|\varphi''\| \}$$

The first term on the right hand side is bounded by

$$(3.20) \quad c_{12} h^{-1/2} |\lambda(\varphi)| \|\varphi''\| \leq \delta \|\varphi''\|^2 + \frac{1}{4\delta} c_{12}^2 h^{-1} |\lambda(\varphi)|^2.$$

The second causes no difficulties. The third can be estimated by

$$(3.21) \quad c_{12} |\lambda(\varphi)| \|\varphi'\| \|\varphi''\| \leq h^{-1} |\lambda(\varphi)|^2 + c_{13} h \|\varphi'\|^2 \|\varphi''\|^2.$$

Because of Proposition 2 we get

$$(3.22) \quad h \|\varphi'\|^2 \|\varphi''\|^2 \leq c_2 \|\varphi'\|^3 \|\varphi''\| \leq \delta \|\varphi''\|^2 + \frac{1}{4\delta} c_2^2 \|\varphi'\|^6.$$

This completes the proof.

Remark: The method discussed has its predecessor in [7].

In order to approximate the solution of the Dirichlet problem of a second order elliptic differential equation we constructed a bilinear-form defined for functions not necessarily fulfilling any boundary conditions. Whereas this form is in general indefinite it is positive definite in the approximation spaces by the aid of certain inverse properties.

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