The Leray-Hopf and the 3D-curl operators

Extract from (LeN)

1. Introduction

The (Marcel) Riesz operators $(R_j)_{1 \le j \le n}$ are the following Fourier multipliers (we use the notation $d\hat{u}$ for the Fourier transform of u: our normalization is given in the formula (3.1) of our appendix)

$$(\widehat{R_j u})(\xi) = \xi_j |\xi|^{-1} \widehat{u}(\xi), R_j = \frac{D_j}{|D|} = (-\Delta)^{-1/2} \frac{\partial}{\partial x_j}.$$

The R_j are selfadjoint bounded operators on $L^2(R^n)$ with norm 1. The riesz operators are the natural multidimensional generalization of the Hilbert transform, given by the convolution with $pv\frac{i}{\pi x}$ which is the one-dimensional Fourier multiplier by $sign(\xi)$. These operators are bounded on $L^p(R^n)$ for $1 and send <math>L^1$ into L^1_ω . However they are not continuous on the Schwartz class, because of the singularity at the origin. The Leray-Hopf projector (that projector is also called the Helmholtz-Weyl projector by some authors) is the following matrix valued Fourier multiplier, given by

$$\boldsymbol{P}(\xi) = Id - \frac{\xi \otimes \xi}{|\xi|^2} = (\delta_{jk} - \frac{\xi_j \xi_k}{|\xi|^2})_{1 \le j,k \le n} , \boldsymbol{P} = Id - R \otimes R =: Id - \boldsymbol{Q}.$$

We can also consider the $n \times n$ matrix of operators given by $\mathbf{Q} := R \otimes R = (R_j R_k)_{1 \le j,k \le n}$ sending the vector space of $L^2(R^n)$ vector fields into itself. The operator Q is selfadjoint and is a projection since $\sum_l R_l^2 = Id$ so that $Q^2 = \sum_l (R_j R_l R_l R_k)_{j,k} = Q$. As a result the (Leray-Hopf or Helmholtz-Weyl) operator

$$\mathbf{P} = Id - R \otimes R =: Id - \mathbf{Q} = Id - \frac{D \otimes D}{D^2} Id - \Delta^{-1}(\nabla \times \nabla)$$

is also an orthogonal projection; the operator is in fact the orthogonal projection onto the closed subspace of L^2 vecor fields with null divergence. We have for a vector field $\sum_l u_j \, \partial_j$, the identity $\operatorname{grad} \operatorname{div} u = \nabla(\nabla \cdot u)$, and thus

grad
$$div = \nabla \otimes \nabla = \Delta R \otimes R$$
, so that

$$Q = R \otimes R = \Delta^{-1} \operatorname{grad} \operatorname{div}, \operatorname{div} R \otimes R = \operatorname{div},$$

which implies $div \, \mathbf{P}u = div \, u \, - div (R \otimes R)u = 0$, and if $div \, u = 0$, we have $\mathbf{Q}u = 0$ and $u = \mathbf{Q}u + \mathbf{P}u = \mathbf{P}u$. This operator plays an important role in fluid mechanics since the Navier-Stokes system for incompressible fluids can be written as

(1.6)
$$\begin{aligned} \partial_t v + \pmb{P}\big((v \cdot \nabla)v\big) - \nu \Delta v &= 0 \\ \pmb{P}((v) = v, \\ v_{|t=0} &= v_0. \end{aligned}$$

(*) $\nu = \frac{\eta}{\rho}$ denotes the kinetical viscosity constant, while η denotes the dynamic viscosity constant, and ρ the density of the fluid).

As already said for the Riesz operators, P is not a classical pseudodifferential operator, because of the singularity at the origin; however it is indeed a Fourier multiplier with the same continuity properties as those of , and in particular is bounded on L^p for $p \in (1, \infty)$. In three dimensions the **curl** operator is given by the matrix

$$\boldsymbol{curl} = \begin{pmatrix} 0 & -\partial_3 & \partial_2 \\ \partial_3 & 0 & -\partial_1 \\ -\partial_2 & \partial_1 & 0 \end{pmatrix} = \boldsymbol{curl}^*$$

so that $curl^2 = -\Delta Id + grad \ div$ and (the Bio-Savard law)

$$Id = (-\Delta)^{-1} curl^2 + \Delta^{-1} grad div = (-\Delta)^{-1} curl^2 + Id - P$$

which gives

$$curl^2 = -\Delta P$$
,

so that [P, curl] = 0 and

$$P curl = curl P = curl (-\Delta)^{-1} curl^2 = curl (Id - \Delta^{-1} grad div) = curl$$

since $curl\ grad = 0$ (note also that the transposition of the latter gives $div\ curl = 0$).

The solutions of (1.6) are satisfying

$$v(t) = e^{\nu t \Delta} - \int_0^t e^{(t-s)\nu \Delta} \mathbf{P} \nabla(v(s) \otimes v(s)) ds.$$

(LeN) Lerner, N. (2009), A Note on the Oseen Kernels. In: Bove, A., Del Santo, D., Murthy, M. (eds) Advances in Phase Space Analysis of Partial Differential Equations. Progress in Nonlinear Differential Equations and Their Applications, vol 78. Birkhäuser Boston

Note: The pressure p of the NSE can be expressed in terms of the velocity u by the formula $p = \sum_{j,k=1}^3 R_j R_k(u_j u_k)$, where $\mathbf{R} \coloneqq (R_1, R_2, R_3)$ is the Riesz transform and $\mathbf{u} \otimes \mathbf{u} = (u_j u_k)$ is a 3x3 matrix.

$$H_{1/2} = H_1 \otimes H_1^{\perp}$$